

Сведения о ведущей организации:

Полное наименование организации	Федеральное государственное бюджетное учреждение науки Институт проблем машиноведения Российской академии наук
Сокращенное наименование организации	ИПМаш РАН
Фамилия, имя, отчество руководителя организации	Полянский Владимир Анатольевич
Должность руководителя организации	директор
Почтовый адрес	199178, г. Санкт-Петербург, Большой проспект В.О., д. 61
Телефон	+7-812-3214778
Адрес официального сайта в сети «Интернет»	www.ipme.ru
Адрес электронной почты	ipmash@ipme.ru
Основные публикации работников организации по теме диссертации в рецензируемых научных изданиях за последние 5 лет (ВАК, Scopus)	<p>1. Furtat I.B, Nekhoroshikh A.N. Modified Backstepping Algorithm and its Application to Control of Distillation Column. Mekhatronika, Avtomatizatsiya, Upravlenie. 2019. T. 20. № 2. С. 90-96. DOI: 10.17587/mau.20.90-96 Scopus</p> <p>2. Furtat I.B. Robust Algorithm for Control of Distillation Column. Proc. of the 4th International Conference on Control, Decision and Information Technologies, University of Barcelona, Barcelona, Spain, 2017. DOI: 10.1109/CoDIT.2017.8102593 Scopus</p> <p>3. Pavel Gushchin, Igor Furtat, Artem Nekhoroshikh, Julia Chugina, Sergey Vrazhevsky, Mikhail Tarasov. Control of distillation column under perturbations: a case study. Cybernetics and Physics, Vol. 9, No. 4. 2020, 182-186. https://doi.org/10.35470/2226-4116-2020-9-4-182-186 Scopus</p> <p>4. Kuchmin, A.Y., Abramyan, A.K., Petrov, Y.V., Smirnov, I.V., Bragov, A.M. Structural-time and pulse characteristics of dynamic fracture of some construction materials Doklady Physics, 2017, 62(1), pp. 27–29.</p>

DOI: 10.1134/S1028335817010049 Scopus

5. Synthesis of Optimal Program Control for Synchronizing the Movements of a Group of SEMS Modules Kuchmin, A.Y. Studies in Systems, Decision and Control, 2021, 352, стр. 81–94 Scopus

6. Кучмин А.Ю. Проблемы идентификации нестационарных динамических объектов. Информационно-управляющие системы. 2018. № 2. С. 18–25. DOI: 10.15217/issnl684-8853.2018.2.28 Scopus

7. Gorodetskiy, A.E., Tarasova, I.L. Logical and Mathematical Method of Making Behavioral Decisions Studies in Systems, Decision and Control, 2021, 352, pp. 3–14. DOI 10.1007/978-3-030-68172-2_1 Scopus

8. Gorodetskiy, A.E., Kurbanov, V.G., Tarasova, I.L. Using Binary Relationships in Decision Making Studies in Systems, Decision and Control, 2021, 352, стр. 29–36. DOI: 10.1007/978-3-030-68172-2_3. Scopus

9. Gorodetskiy, A.E., Tarasova, I.L. Decision Making an Autonomous Robot Based on Matrix Solution of Systems of Logical Equations that Describe the Environment of Choice for Situational Control Studies in Systems, Decision and Control, 2020, 261, стр. 259–273. DOI: 10.1007/978-3-030-32710-1_20. Scopus

10. Furtat, I., Fridman, E. Delayed Disturbance Attenuation via Measurement Noise Estimation. IEEE Transactions on Automatic Control, 2021, 66(11), pp. 5546–5553. DOI:10.1109/TAC.2021.3054238. Scopus

11. Furtat, I.B., Nekhoroshikh, A.N., Gushchin, P.A. Robust Stabilization of Linear Plants in the Presence of Disturbances and High-Frequency Measurement Noise. Automation and Remote Control, 2021, 82(7), pp. 1248–1261. DOI:10.1134/S0005117921070080. Scopus

12. Furtat, I.B., Gushchin, P.A. Control of Dynamical Plants with a Guarantee for the Controlled Signal to Stay in a Given Set. Automation and Remote Control, 2021, 82(4), pp. 654–669. DOI: 10.1134/S0005117921040044. Scopus.

	<p>13. Furtat, I.B., Gushchin, P.A. Spatially Discrete Control of Scalar Linear Distributed Plants of Parabolic and Hyperbolic Types Automation and Remote Control, 2021, 82(3), pp. 433–448. DOI:10.1134/S0005117921030048. Scopus.</p> <p>14. Furtat, I., GushchinP. Stability study and control of nonautonomous dynamical systems based on divergence conditions, Journal of the Franklin Institute, 2020, 357(18), pp. 13753–13765. DOI10.1016/j.jfranklin.2020.10.025. Scopus</p> <p>15. Andrievsky, B.R., Furtat, I.B. Disturbance Observers: Methods and Applications. II. Applications Automation and Remote Control, 2020, 81(10), pp. 1775–1818. DOI:10.1134/S0005117920100021. Scopus.</p>
--	--